

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings of claims in the application:

LISTING OF CLAIMS:

1-14. (canceled).

15. (currently amended) Method for operating a tracking device operatively connected to a container and having at a remote communication device, comprising the steps of:

performing a positioning information obtaining procedure concerning said container;

sensing whether said tracking device is in proximity to an aircraft by ; ~~said step of sensing in turn comprising the step of detecting electromagnetic fields emitted by said aircraft;~~

disabling emission of radio frequency signals from said remote communication device if proximity to ~~[[an]]~~ said aircraft is indicated in said step of sensing; and

re-enabling emission of radio frequency signals from said remote communication device only if a lack of electromagnetic fields emitted by said aircraft is established ~~proximity to an aircraft is indicated in said step of sensing~~ simultaneously as ~~said step of performing~~ a positioning information obtaining procedure is ~~successful~~ successfully performed.



16. (currently amended) Method according to claim 15, comprising the further steps of: [[:]]

measuring a time period during which lack of proximity to [[an]] the aircraft continuously is indicated in said step of sensing; and

re-enabling emission of radio frequency signals from said remote communication device if said time period exceeds a predetermined value.

17. (previously presented) Method according to claim 16, wherein said predetermined value is larger than a maximum flight time from a globally most remote flight position.

18. (previously presented) Method according to claim 17, wherein said predetermined value is larger than a maximum flight time for said aircraft on battery backup.

19. (previously presented) Method according to claim 15, wherein said step of performing a positioning information obtaining procedure in turn comprises the step of determining a GPS position.

20. (previously presented) Method according to claim 15, wherein said step of detecting in turn comprises the step of



detecting electromagnetic field frequencies in the range of 400 Hz.

21. (currently amended) Tracking device for remote monitoring of a container to which said tracking device is operatively connected, said tracking device comprising:

a positioning system to obtain positioning information concerning said container;

a remote communication device;

a control system connected to said positioning system and said remote communication device; and

a detector for sensing whether said tracking device is in proximity to an aircraft and comprising an electromagnetic field sensor, sensing electromagnetic fields emitted by said aircraft, said detector being connected to said control system,

~~;~~ ~~said detector comprising an electromagnetic field sensor, sensing electromagnetic fields emitted by said aircraft;~~

said control system being arranged to disable emission of radio frequency signals from said remote communication device responsive to an output of said detector indicating proximity to [[an]] said aircraft, and

said control system being arranged to re-enable emission of radio frequency signals from said remote communication device only responsive to a simultaneously established lack of an output of electromagnetic fields emitted



by said aircraft and a successfully performed positioning information obtaining procedure by ~~said detector indicating proximity to an aircraft simultaneously as~~ said positioning system being able to obtain the positioning information.

22. (previously presented) Tracking device according to claim 21, wherein said control system being arranged to also re-enable emission of radio frequency signals from said remote communication device responsive to a lack of an output of said detector indicating proximity to an aircraft during a time period exceeding a predetermined value.

23. (previously presented) Tracking device according to claim 22, wherein said control system further comprises a timer arranged to clock said time period.

24. (previously presented) Tracking device according to claim 22, wherein said predetermined value is larger than a maximum flight time from a globally most remote flight position.

25. (previously presented) Tracking device according to claim 24, wherein said predetermined value is larger than a maximum flight time on battery backup.



26. (previously presented) Tracking device according to 21, wherein said positioning system is a GPS system.

27. (previously presented) Tracking device according to claims 21, wherein said electromagnetic field sensor is arranged to sense electromagnetic field frequencies in the range of 400 Hz.

28. (currently amended) Container for airfreight, having tracking device for remote monitoring of said container, said tracking device comprising:

a positioning system to obtain positioning information concerning said container;

a remote communication device; control system connected to said positioning system and said remote communication device; and

a detector for sensing whether said container is in proximity to an aircraft and comprising an electromagnetic field sensor, sensing electromagnetic fields emitted by said aircraft, said detector being connected to said control system,

~~;~~ ~~said detector comprising an electromagnetic field sensor, sensing electromagnetic fields emitted by said aircraft;~~

said control system being arranged to disable emission of radio frequency signals from said remote communication device



responsive to an output of said detector indicating proximity to an aircraft;

said control system being arranged to re-enable emission of radio frequency signals from said remote communication device only responsive to a simultaneously established lack of electromagnetic fields emitted by said aircraft and successfully performed positioning information obtaining procedure by ~~an output of said detector indicating proximity to an aircraft simultaneously as~~ said positioning system being able to obtain the positioning information.